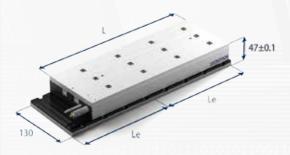
# THE LINEAR MOTOR COMPANY

## TBW Series Iron Core

|             | Parameter                            | Remarks                  | Symbol           | Unit               | TBW18   |      | TBW30     |        | TBW45 |      |  |
|-------------|--------------------------------------|--------------------------|------------------|--------------------|---|------|-----------|--------|-------|------|--|
|             | Winding type                         |                          |                  |                    | N   | S    | N         | S      | N     | S    |  |
| Performance | Motortype, max voltage ph-ph         |                          |                  |                    | 3-phase synchronous Iron core, 400V <sub>ac rms</sub> (600V <sub>dc</sub> ) |      |           |        |       |      |  |
|             | Ultimate Force @ 10°C/s increase     | magnet @ 25°C            | Fu               | N                  | 2700 4  |      | 500       | 0 6750 |       |      |  |
|             | Peak Force @ 6°C/s increase          | magnet @ 25°C            | Fp               | N                  | 2400  |      | 40        | 4000   |       | 6000 |  |
|             | Continuous Force Watercooled*        | coils @ 100°C            | F <sub>cw</sub>  | N                  | 1200  |      | 2000      |        | 3000  |      |  |
| Perf        | Continuous Force Aircooled*          | coils @ 100°C            | F <sub>c</sub>   | N                  | 1140  |      | 19        | 1900   |       | 2850 |  |
|             | Maximum Speed**                      | @ 560 V                  | V <sub>max</sub> | m/s                | 3   | 6    | 2.5       | 6      | 2.5   | 6    |  |
|             | Motor Force Constant                 | mount. sfc. @ 20°C       | K                | N/A <sub>rms</sub> | 186   | 90   | 225       | 93     | 225   | 93   |  |
|             | Motor Constant                       | coils @ 25°C             | S                | N <sup>2</sup> /W  | 2580  |      | 4300      |        | 6450  |      |  |
|             | Ultimate Current                     | magnet @ 25°C            | l <sub>u</sub>   | A <sub>rms</sub>   | 19.6  | 41   | 27        | 65     | 41    | 98   |  |
|             | Peak Current                         | magnet @ 25°C            | Ip               | A <sub>rms</sub>   | 15.0  | 31.1 | 20.7      | 50     | 31    | 75   |  |
| [a]         | Continuous Current Watercooled*      | coils @ 100°C            | I <sub>cw</sub>  | A <sub>rms</sub>   | 6.5   | 13.4 | 8.9       | 21.5   | 13.4  | 32.3 |  |
| Electrical  | Back EMF Phase-Phase <sub>peak</sub> |                          | B <sub>emf</sub> | V/m/s              | 152   | 76   | 183       | 76     | 183   | 76   |  |
| 畫           | Resistance per Phase*                | coils @ 25°C ex. cable   | R <sub>ph</sub>  | Ω                  | 4.4   | 1.0  | 3.9       | 0.66   | 2.6   | 0.44 |  |
|             | Induction per Phase                  | I < 0.6 lp               | L <sub>ph</sub>  | mH                 | 35  | 8    | 31        | 5      | 21    | 3    |  |
|             | Electrical Time Constant*            | coils @ 25°C             | τ <sub>e</sub>   | ms                 |   | 8    |           | 8      |       | 8    |  |
| Thermal     | Maximum Continuous Power Loss        | all coils                | P <sub>c</sub>   | W                  | 726   |      | 1209      |        | 1804  |      |  |
|             | Thermal Resistance                   | coils to mount. sfc.     | R <sub>th</sub>  | °C/W               | 0.10  |      | 0.06      |        | 0.04  |      |  |
|             | Thermal Time Constant*               | up to 63% max. coiltemp. | $\tau_{th}$      | S                  | 87  |      | 8         | 87     |       | 87   |  |
| The         | Watercooling Flow                    | for ΔT=3K                | Фw               | l/min              | 3.1   |      | 5         | .2     | 7.8   |      |  |
|             | Watercooling Pressure-drop           | order of magnitude       | ΔP <sub>w</sub>  | bar                | 1.0 1.5   |      | .5        | 2.5    |       |      |  |
|             | Temperature Cut-off / Sensor         |                          |                  |                    | PTC 1kΩ / KTY 83-122  |      |           |        |       |      |  |
| Mechanical  | Coil Unit Weight                     | ex. cables               | W                | kg                 | 7.3   |      | 12.3      |        | 18.2  |      |  |
|             | Coil Unit Length                     | ex. cables               | L                | mm                 | 344   |      | 580       |        | 852   |      |  |
|             | Motor Attraction Force               | rms @ 0 A                | Fa               | N                  | 4900  |      | 8300      |        | 12450 |      |  |
|             | Magnet Pitch NN                      |                          | τ                | mm                 | 24  |      | 24        |        | 24    |      |  |
|             | Cable Mass                           |                          | m                | kg/m               | 0.3   |      |           |        | 0.6   |      |  |
|             | Cable Type (Power)                   | length 1 m               | d                | mm (AWG)           | 11.9 (14)   |      | 16.9 (10) |        |       |      |  |
|             | Cable Type (Sensor)                  | length 1 m               | d                | mm (AWG)           | 4.3 (26)  |      |           |        |       |      |  |



TBW18 on 2x192mm magnet plate shown

Approvals

C E Dus RoHS

See page 28 for Analog hall

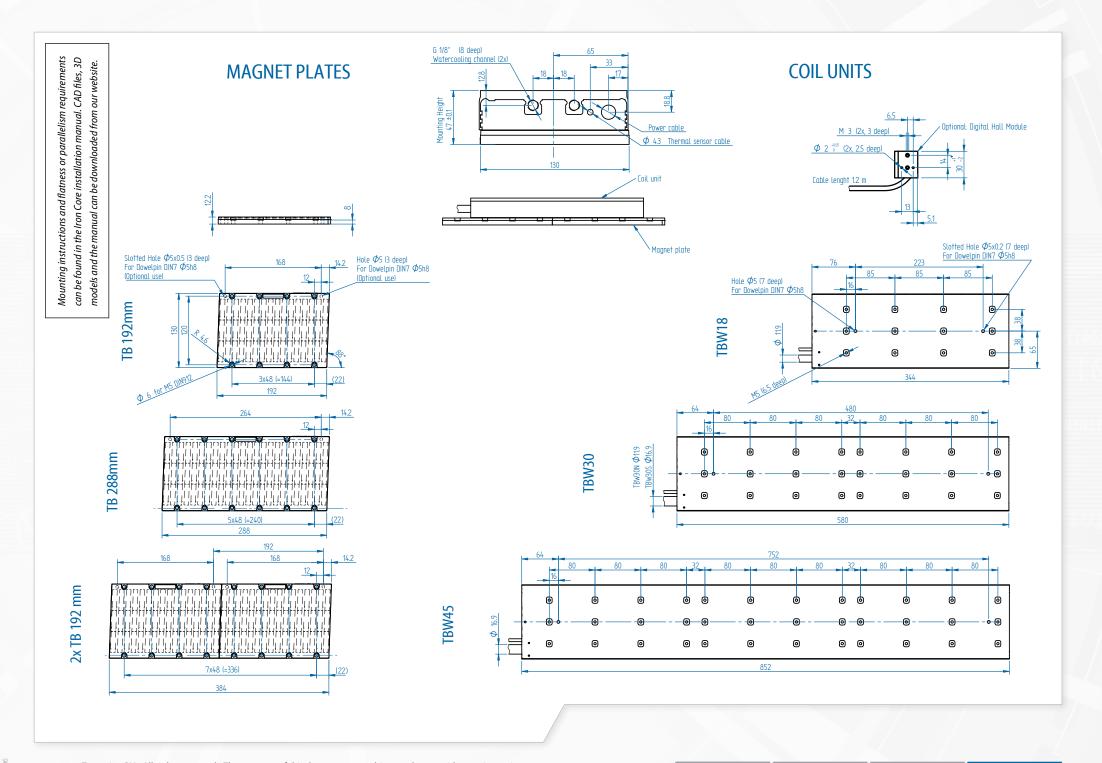
#### Water cooling

All TBW motors feature integrated cooling channels that allow for the easy setup of a liquid cooled system, at no additional cost.

| Magnet plate dimensions               |      |     |  |  |  |  |  |  |  |
|---------------------------------------|------|-----|--|--|--|--|--|--|--|
| Le (mm)                               | 192  | 288 |  |  |  |  |  |  |  |
| M5 bolts                              | 8    | 12  |  |  |  |  |  |  |  |
| Mass (kg/m)                           | 10.5 |     |  |  |  |  |  |  |  |
| Magnet plates can be butted together. |      |     |  |  |  |  |  |  |  |

<sup>\*</sup>These values are only applicable when the mounting surface is at 20°C and the motor is driven at maximum continuous current. If these values differ in your application, please check our simulation tool.

<sup>\*\*</sup> Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.



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### [ DIRECT DRIVE ADVANTAGES ]

The direct drive technology of linear motors is a perfect way to enhance productivity, accuracy, and dynamic performance. Linear motors eliminate the need for mechanical transmissions like rack and pinion, belts and speed reducers. Between coil unit and magnets there is no contact, this means no mechanical wear. The technology makes designs slimmer, modular and reduces costs.

#### Modular system. All motors can be used in various configurations:











1. single moving coil

2. moving magnet

3. parallel coupled coil

4. in-line on a single track

5. crosstable or gantry

#### High force density

More force in a smaller packing means lowering footprint and fits better in smal(ler) spaces.

#### Low cogging

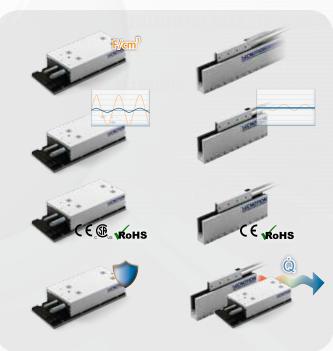
Optimized iron core motor design, for smooth motion and position accuracy in your application.

#### Approved for CSA and CE, ROHS

Iron core motors are approved for CE, CSA and ROHS.

#### Aluminium housed design

Housed design with integrated water cooling for TBW- and TL series.



#### High acceleration and dynamics

The outstanding force to mass ratio of the ironless coils enables unmatched system dynamics.

#### No cogging, extremely low force ripple

Ironless motors have no cogging effects. Offering smooth motion and position accuracy in your application.

#### Approved for CE and ROHS

Ironless motors are CE and RoHS approved.

#### Low thermal resistance

Allowing good heat transfer, achieving an extremely high continuous force for all motors when using a descent size heatsink or active cooling.