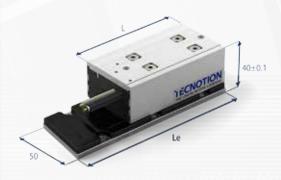
TECNOTION THE LINEAR MOTOR COMPANY

TM Series Iron Core

	Parameter	Remarks	Sym	Unit	TM3	TM6	TM12	TN	118
	Winding type				S	S	S	N	S
Performance	Motortype, max voltage ph-ph				3-phase synchronous Iron core, 400V _{ac rms} (600V _{dc})				
	Ultimate Force @ 10°C/s increase	magnet @ 25°C	F _u	N	120	240	480	720	
	Peak Force @ 6°C/s increase	magnet @ 25°C	Fp	N	105	210	420	630	
	Continuous Force*	coils @ 100°C	F _c	N	60	120	240	360	
	Maximum Speed**	@ 600 V	V _{max}	m/s	12	12	12	4.5	10.0
	Motor Force Constant	mount. sfc. @ 20°C	K	N/A _{rms}	39	39	39	79	39
	Motor Constant	coils @ 25°C	S	N ² /W	95	190	380	570	
	Ultimate Current	magnet @ 25°C	Iu	A _{rms}	4.1	8.2	16.4	12.3	25.1
le:	Peak Current	magnet @ 25°C	Ip	A _{rms}	3.1	6.2	12.4	9.2	18.9
	Maximum Continuous Current*	coils @ 100°C	I _c	A _{rms}	1.5	3	6	4.5	9.3
Electrical	Back EMF Phase-Phase _{peak}		B _{emf}	V/m/s	32	32	32	65	32
Ħ,	Resistance per Phase*	coils @ 25°C ex. cable	R _{ph}	Ω	5.4	2.7	1.35	3.6	0.85
	Induction per Phase	I < 0.6 lp	L _{ph}	mH	35	17	9	23	5.5
	Electrical Time Constant*	coils @ 25°C	τ _e	ms	6.5	6.5	6.5	6.5	
Thermal	Maximum Continuous Power Loss	all coils	P _c	W	49	99	197	296	
	Thermal Resistance	coils to mount. sfc.	R _{th}	°C/W	1.5	0.75	0.38	0.25	
<u>e</u>	Thermal Time Constant*	up to 63% max. coiltemp.	τ_{th}	S	75	75	75	75	
	Temperature Cut-off / Sensor				PTC 1kΩ / KTY 83-122				
	Coil Unit Weight	ex. cables	W	kg	0.6	0.9	1.6	2	.3
Mechanical	Coil Unit Length	ex. cables	L	mm	93	143	241	336	
	Motor Attraction Force	rms @ 0 A	Fa	N	300	500	900	1300	
	Magnet Pitch NN		τ	mm	24	24	24	2	4
	Cable Mass		m	kg/m	0.18	0.18	0.18	0.	18
	Cable Type (Power FLEX)	length 3 m	d	mm (AWG)	8.3 (≥18)				
	Cable Type (Sensor)	length 3 m	d	mm (AWG)	4.3 (26)				
	Cable Life (Power FLEX)***	minimum				5,000,000 cycles			
	Bending Radius Static	minimum			4x cable diameter				
	Bending Radius Dynamic	minimum			10x cable diameter				



TM3 on 144mm magnet plate shown

CE & VROHS See page 28 for Analog hall

FLEX Cable

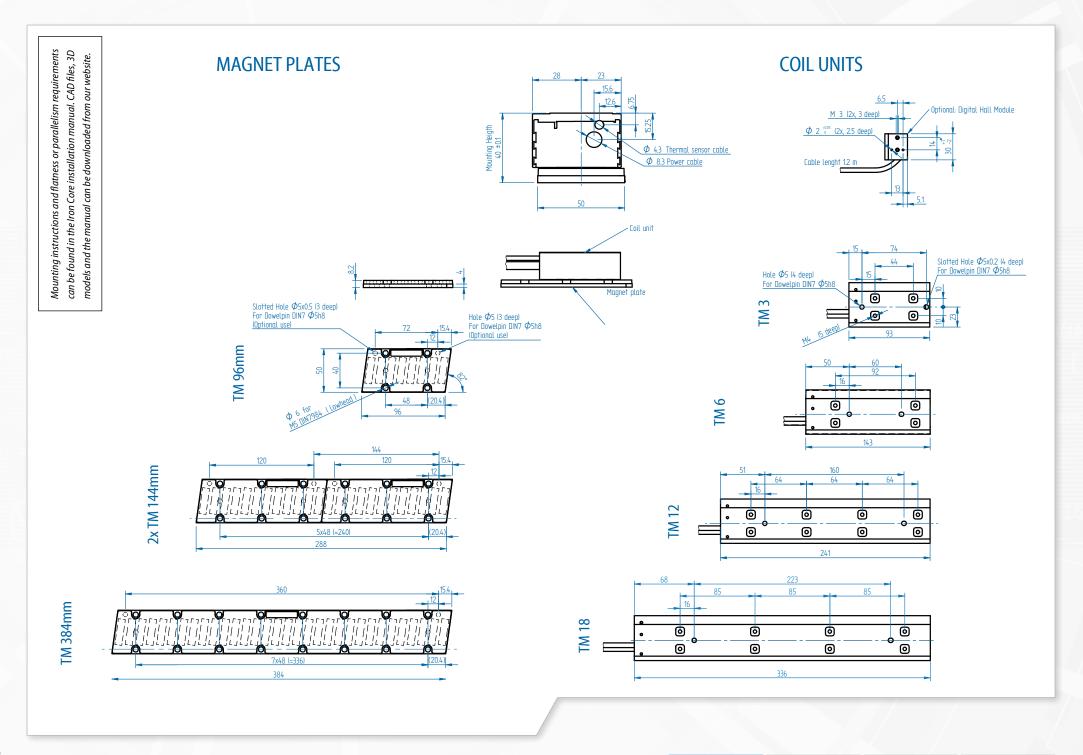
The TM series comes standard with a 3m long FLEX power cable.

Magnet plate dimensions									
Le (mm)	96	144	384						
M5 bolts	4	6	16						
Mass (kg/m)	2.1								
Magnet plates can be butted together.									

^{*}These values are only applicable when the mounting surface is at 20°C and the motor is driven at maximum continuous current. If these values differ in your application, please check our simulation tool.

^{**} Actual values depend on bus voltage. Please check the F/v diagram in our simulation tool.

^{***} Depending on Bending Radius, Velocity and Acceleration.



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[DIRECT DRIVE ADVANTAGES]

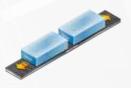
The direct drive technology of linear motors is a perfect way to enhance productivity, accuracy, and dynamic performance. Linear motors eliminate the need for mechanical transmissions like rack and pinion, belts and speed reducers. Between coil unit and magnets there is no contact, this means no mechanical wear. The technology makes designs slimmer, modular and reduces costs.

Modular system. All motors can be used in various configurations:











1. single moving coil

2. moving magnet

3. parallel coupled coil

4. in-line on a single track

5. crosstable or gantry

High force density

More force in a smaller packing means lowering footprint and fits better in smal(ler) spaces.

Low cogging

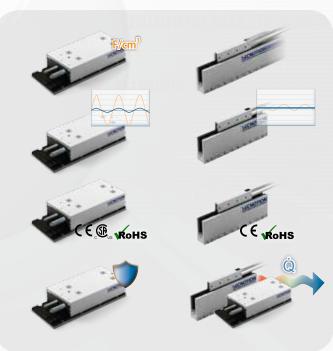
Optimized iron core motor design, for smooth motion and position accuracy in your application.

Approved for CSA and CE, ROHS

Iron core motors are approved for CE, CSA and ROHS.

Aluminium housed design

Housed design with integrated water cooling for TBW- and TL series.



High acceleration and dynamics

The outstanding force to mass ratio of the ironless coils enables unmatched system dynamics.

No cogging, extremely low force ripple

Ironless motors have no cogging effects. Offering smooth motion and position accuracy in your application.

Approved for CE and ROHS

Ironless motors are CE and RoHS approved.

Low thermal resistance

Allowing good heat transfer, achieving an extremely high continuous force for all motors when using a descent size heatsink or active cooling.