

T E C H N O S O F T MOTION TECHNOLOGY

# iPOS8010 BX-CAN INTELLIGENT SERVO DRIVE 10A, 80VDC

# FOR BRUSHLESS, BRUSHED, LINEAR OR STEP MOTORS

#### **D**ESCRIPTION

The iPOS8010 BX-CAN is a new member of the iPOS family of Technosoft intelligent drives. It is based on a new design concept for closed-frames drives, offering a very compact and cost effective solution for the control of rotary or linear brushless, DC brush, and step motors of powers up to 800 W.

Designed to cover low to medium volume applications, the iPOS8010 BX-CAN embeds motion controller, drive, and PLC functionalities into a single unit.

When used as an intelligent drive - like all other members of the iPOS family - the iPOS8010 BX-CAN is empowered by the extreme flexibility offered by the TML (Technosoft Motion Language) instruction set. The unit can replace a host in various single or multi-axis stand-alone applications.

Advanced positioning profiles like the PVT or electronic caming, I/O and program flow control, data transfer between axes, subroutines, ISRs and multiple homing modes ease the motion application implementation task.

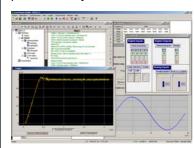
In systems that require a host, the iPOS operates as an intelligent slave executing motion sequences triggered via commands received on RS-232 or CAN while fully supporting as well the CiA402 CANopen drive profile.

### **DUAL LOOP**

Equipped with 2 feedback connectors, the iPOS8010 BX-CAN provides advanced dual-loop control schemes that minimize the transmission backlash negative effects

### EASYMOTION STUDIO

The configuration, tuning and programming of the iPOS8010 BX-CAN drive is easy with Technosoft's powerful graphical platform, EasyMotion Studio.



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### FEATURES:

- Motion controller and drive in a single compact unit
- Universal drive solution for brushless, brushed, linear or step (true closed loop) motors
- Advanced motion control capabilities (PVT, S-curve, electronic cam)
- Motion programming via TML (Technosoft Motion Language) or motion libraries for Visual C / VB / LabVIEW / Linux and PLC
- Standalone operation with stored motion sequences
- · Drive enable circuit
- Communication:
  - RS-232 serial
  - CAN-Bus with TMLCAN or CANopen (CiA301, 305, 402) protocols
- Digital and analogue I/Os:
  - 4 PNP/NPN digital programmable inputs, 24 V
  - 4 NPN digital outputs, 5 36 V, 0.5 A
  - 2 analogue inputs: 12 bit resolution, 0 5 V
- Feedback devices (dual-loop supported) :
  1st Feedback :
  - Incremental quad encoder ( differential )
  - Analogue sine/cosine encoder (differential 1Vpp)
  - Digital Hall sensors

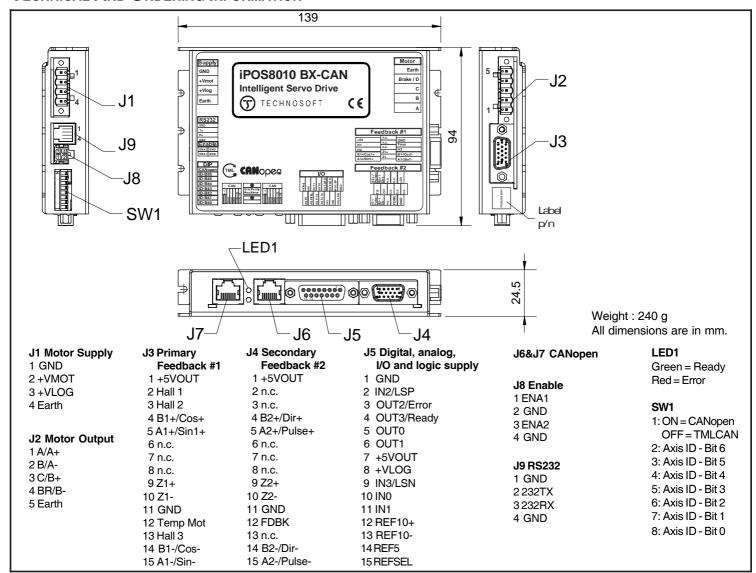
#### 2<sup>nd</sup> Feedback:

- Incremental quad encoder ( differential )
- Protections:
  - Over-current, over-temperature, short circuit
  - Over and undervoltage, i2t, control error

### **ELECTRICAL SPECIFICATIONS:**

Motor power supply:	12 - 80 VDC
Logic supply :	12 - 36 VDC
Continuous phase current	10A
Peak current (10 sec. max.)	20 A
PWM switching frequency	20 - 60 kHz
Ambient operating temperature	0 °C - 40 °C

### TECHNICAL AND ORDERING INFORMATION



The high level graphical development environment EasyMotion Studio supports the configuration, parameterization and programming of the drive, through:

- · Motion system set-up wizard
- Tuning assistance with capture functions
- Definition, programming and testing of motion sequences

### MOTION CONTROL LIBRARIES

The TML\_LIB Motion Control Libraries can be used to implement a motion control application on a PC from Visual C / C++, C#, Visual Basic, Delphi or LabVIEW under Windows or Linux operating systems.

If a PLC is used as host, implementations of the TML\_LIB according with IEC-61131 standard are available for Siemens, B&R and Omron PLCs.

**Application notes** with TML program examples at : www.technosoftmotion.com

### **ORDERING INFORMATION:**

	iPOS8010 BX-CAN, 80V,10A, cl. frame, Enc, CAN
PU34.001.E002	EasyMotion Studio Software
P040.001.Exxx	TML_LIB Motion Library*

\*ask for existing libraries types

### FLEXIBILITY:

Control schemes supported by the iPOS8010 BX-CAN Drive

Motor types	Torque Control	Speed Control	Position Control *
Brushless	1	<b>V</b>	√
Brushed	1	√	√
Step	1	<b>V</b>	4
Linear	٧	√	4

\* Dual-loop control supported

### **CONNECTORS Type and Mating Connectors:**

Connector	Mating connectors	
J1	CTBA9208/4FL CAMDEN-Boss	
J2	CTBA9208/5FL CAMDEN-Boss	
J3, J4	High Density D-Sub male, 15 pins	
J5	D-Sub male, 15 pins	
J6, J7	RJ-45 plug	
J8	Molex 43045-0400	
J9	RJ-10 plug	

## SALES OFFICES

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